





HAC T-Coil TEST REPORT

No.I23Z60867-SEM03

For

TCL Communication Ltd.

GSM Mobile phone

Model Name: T302D, T302X

With

Hardware Version: V1.0

Software Version: V1.1

FCC ID: 2ACCJB209

Results Summary: T Category = T4

Issued Date: 2023-05-25

Note

The test results in this test report relate only to the devices specified in this report. This report shall not be reproduced except in full without the written approval of CTTL.

Test Laboratory:

CTTL, Telecommunication Technology Labs, CAICT

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REPORT HISTORY

Report Number	Revision	Issue Date	Description
I23Z60867-SEM03	Rev.0	2023-05-25	Initial creation of test report





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1 Test Laboratory

1.1 Testing Location

Company Name:	CTTL
Address:	No. 52, Huayuan North Road, Haidian District, Beijing, P. R. China
	100191.

1.2 Testing Environment

Temperature:	18°C~25°C,
Relative humidity:	30%~ 70%
Ground system resistance:	< 0.5 Ω

Ambient noise is checked and found very low and in compliance with requirement of standards Reflection of surrounding objects is minimized and in compliance with requirement of standards

1.3 Project Data

Project Leader:	Qi Dianyuan
Test Engineer:	Wang Tian
Testing Start Date:	May 9, 2023
Testing End Date:	May 10, 2023

1.4 Signature

Wang Tian

(Prepared this test report)

Qi Dianyuan

(Reviewed this test report)

Lu Bingsong

Deputy Director of the laboratory (Approved this test report)





2 Client Information

2.1 Applicant Information

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2.2 Manufacturer Information

Company Name:	TCL Communication Ltd.	
Address/Post:	5/F, Building 22E, 22 Science Park East Avenue, Hong Kong Science	
	Park, Shatin, NT, Hong Kong	
Contact Person:	Annie Jiang	
Contact Email:	nianxiang.jiang@tcl.com	
Telephone:	0086-755-3661 1621	
Fax	0086-755-36612000-81722	





3 Equipment Under Test (EUT) and Ancillary Equipment (AE)

3.1 About EUT

Description:	GSM Mobile phone
Model name:	T302D, T302X
Operating mode(s):	GSM850/900/1800/1900,BT

3.2 Internal Identification of EUT used during the test

EUT ID*	IMEI	HW Version	SW Version
EUT1	351052820007439	V1.0	V1.1
EUT2	351052820001838	V1.0	V1.1

^{*}EUT ID: is used to identify the test sample in the lab internally.

3.3 Internal Identification of AE used during the test

AE ID*	Description	Model	SN	Manufacturer
AE1 Battery		TLi010EA	,	Zhongshan Tianmao Battery
ALI	Battery	TLIUTUEA	\	Co.,Ltd.
AF2	Pattony	TLi010CA	,	Zhongshan Tianmao Battery
AE2 Battery	TLIOTOCA	\	Co.,Ltd.	
AE3 Battery		TI:040CD	\	Shenzhen Aerospace Electronic
		TLi010CB		Co., Ltd.
AF4	Dottoni	TLi010EB		Shenzhen Aerospace Electronic
AE4	Battery			Co., Ltd.
AE5	Headset	805-T28700000	\	JUWEI

^{*}AE ID: is used to identify the test sample in the lab internally.

3.4 Air Interfaces / Bands Indicating Operating Modes

Air-interface	Band(MHz)	Туре	C63.19/tested	Simultaneous Transmissio ns	Name of Voice Service
GSM	850	VO	Yes	ВТ	CMRS Voice
	1900				
BT	2450	DT	NA	GSM	NA

NA: Not Applicable VO: Voice Only V/D: CMRS and IP Voice Service over Digital Transport DT: Digital Transport

Note1 = No Associated T-Coil measurement has been made in accordance with 285076 D02 T-Coil testing for CMRS IP

^{*} HAC Rating was not based on concurrent voice and data modes, Non current mode was found to represent worst case rating for both M and T rating





4 Reference Documents

The following document listed in this section is referred for testing.

Reference	Title	Version
ANSI C63.19-2011	American National Standard for Methods of Measurement	
	of Compatibility between Wireless Communication Devices I	
	and Hearing Aids	
KDB285076	Equipment Authorization Guidance for Hearing Aid	2022
D01v06r02	Compatibility	Edition
	Guidance for performing T-Coil tests for air interfaces	2022
KDB285076 D02v04	supporting voice over IP (e.g., LTE and WiFi) to support	2022 Edition
	CMRS based telephone services	Euilion





5 OPERATIONAL CONDITIONS DURING TEST

5.1 HAC MEASUREMENT SET-UP

These measurements are performed using the DASY5 NEO automated dosimetric assessment system. It is made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland. It consists of high precision robotics system (Stäubli), robot controller, Intel Core2 computer, near-field probe, probe alignment sensor. The robot is a six-axis industrial robot performing precise movements. A cell controller system contains the power supply, robot controller, teach pendant (Joystick), and remote control, is used to drive the robot motors. The PC consists of the HP Intel Core21.86 GHz computer with Windows XP system and HAC Measurement Software DASY5 NEO, A/D interface card, monitor, mouse, and keyboard. The Stäubli Robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE)circuit performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card.

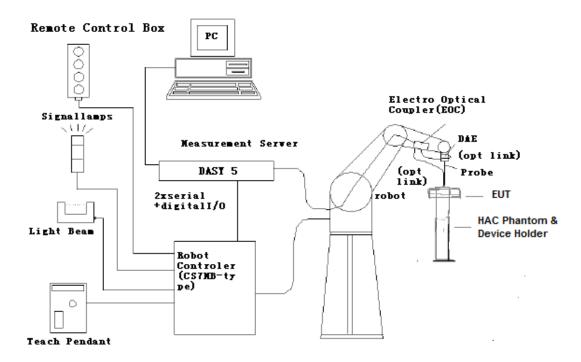


Figure 5.1 HAC Test Measurement Set-up

The DAE4 consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.





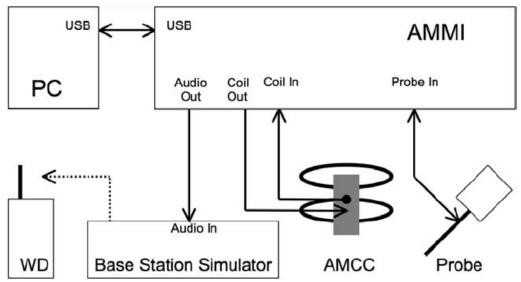


Figure 5.2 T-Coil setup with HAC Test Arch and AMCC

5.2 AM1D probe

The AM1D probe is an active probe with a single sensor. It is fully RF-shielded and has a rounded tip 6mm in diameter incorporating a pickup coil with its center offset 3mm from the tip and the sides. The symmetric signal preamplifier in the probe is fed via the shielded symmetric output cable from the AMMI with a 48V "phantom" voltage supply. The 7-pin connector on the back in the axis of the probe does not carry any signals. It is mounted to the DAE for the correct orientation of the sensor. If the probe axis is tilted 54.7 degree from the vertical, the sensor is approximately vertical when





the signal connector is at the underside of the probe (cable hanging downwards). Specification:

Frequency range	0.1~20kHz (RF sensitivity < -100dB, fully RF shielded)
Sensitivity	< -50dB A/m @ 1kHz
Pre-amplifier	40dB, symmetric
Dimensions	Tip diameter/length: 6/290mm, sensor according to ANSI-C63.19

5.3 AMCC

The Audio Magnetic Calibration coil is a Helmholtz Coil designed for calibration of the AM1D probe. The two horizontal coils generate a homogeneous magnetic field in the z direction. The DC input resistance is adjusted by a series resistor to approximately 50Ohm, and a shunt resistor of 10Ohm permits monitoring the current with a scale of 1:10

Port description:

Signal	Connector	Resistance
Coil In	BNC	Typically 50Ohm
Coil Monitor	BNO	10Ohm±1% (100mV corresponding to 1 A/m)

Specification:

Dimensions	370 x 370 x 196 mm, according to ANSI-C63.19
Difficitions	or o x or o x roo min, according to rate of coc. To

5.4 AMMI



Figure 5.3 AMMI front panel

The Audio Magnetic Measuring Instrument (AMMI) is a desktop 19-inch unit containing a sampling unit, a waveform generator for test and calibration signals, and a USB interface.

Specification:

Sampling rate	48 kHz / 24 bit
Dynamic range	85 dB
Test signal generation	User selectable and predefined (vis PC)
Calibration	Auto-calibration / full system calibration using AMCC with monitor output
Dimensions	482 x 65 x 270 mm

5.5 Test Arch Phantom & Phone Positioner

The Test Arch phantom should be positioned horizontally on a stable surface. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. It enables easy and well defined positioning of the phone and validation dipoles as well as simple teaching of the robot (Dimensions: $370 \times 370 \times 370 \text{ mm}$).

The Phone Positioner supports accurate and reliable positioning of any phone with effect on near ©Copyright. All rights reserved by CTTL. Page 10 of 31



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field $<\pm 0.5$ dB.

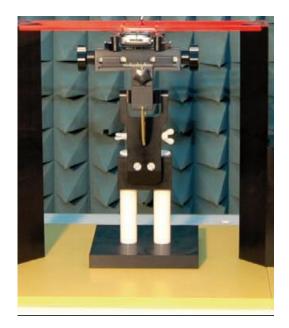


Figure 5.4 HAC Phantom & Device Holder

5.6 Robotic System Specifications

Specifications

Positioner: Stäubli Unimation Corp. Robot Model: RX160L

Repeatability: ±0.02 mm

No. of Axis: 6

Data Acquisition Electronic (DAE) System

Cell Controller

Processor:Intel Core2 Clock Speed: 1.86GHz

Operating System: Windows XP

Data Converter

Features: Signal Amplifier, multiplexer, A/D converter, and control logic

Software: DASY5 software

Connecting Lines: Optical downlink for data and status info.

Optical uplink for commands and clock

5.7 T-Coil measurement points and reference plane

Figure 6.5 illustrates the standard probe orientations. Position 1 is the perpendicular orientation of the probe coil; orientation 2 is the transverse orientations. The space between the measurement positions is not fixed. It is recommended that a scan of the WD be done for each probe coil orientation and that the maximum level recorded be used as the reading for that orientation of the probe coil.

1) The reference plane is the planar area that contains the highest point in the area of the phone that normally rests against the user's ear. It is parallel to the centerline of the receiver area of the





phone and is defined by the points of the receiver-end of the WD handset, which, in normal handset use, rest against the ear.

- 2) The measurement plane is parallel to, and 10 mm in front of, the reference plane.
- 3) The reference axis is normal to the reference plane and passes through the center of the receiver speaker section (or the center of the hole array); or may be centered on a secondary inductive source. The actual location of the measurement point shall be noted in the test report as the measurement reference point.
- 4) The measurement points may be located where the axial and radial field intensity measurements are optimum with regard to the requirements. However, the measurement points should be near the acoustic output of the WD and shall be located in the same half of the phone as the WD receiver. In a WD handset with a centered receiver and a circularly symmetrical magnetic field, the measurement axis and the reference axis would coincide.
- 5) The relative spacing of each measurement orientation is not fixed. The axial and two radial orientations should be chosen to select the optimal position.
- 6) The measurement point for the axial position is located 10 mm from the reference plane on the measurement axis. The actual location of the measurement point shall be noted in test reports and designated as the measurement reference point.

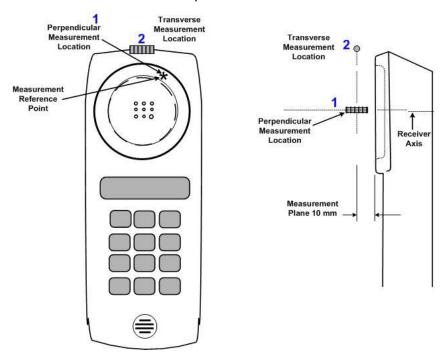


Figure 5.5 Axis and planes for WD audio frequency magnetic field measurements





6 T-Coil TEST PROCEDUERES

The following illustrate a typical test scan over a wireless communications device:

- 1) Geometry and signal check: system probe alignment, proper operation of the field probe, probe measurement system, other instrumentation, and the positioning system was confirmed. A surface calibration was performed before each setup change to ensure repeatable spacing and proper maintenance of the measurement plane using the test Arch.
- 2) Set the reference drive level of signal voice defined in C63.19 per 7.4.2.1.
- 3) The ambient and test system background noise (dB A/m) was measured as well as ABM2 over the full measurement. The maximum noise level must be at least 10dB below the limit.
- 4) The DUT was positioned in its intended test position, acoustic output point of the device perpendicular to the field probe.
- 5) The DUT operation for maximum rated RF output power was configured and connected by using of coaxial cable connection to the base station simulator at the test channel and other normal operating parameters as intended for the test. The battery was ensured to be fully charged before each test. The center sub-grid was centered over the center of the acoustic output (also audio band magnetic output, if applicable). The DUT audio output was positioned tangent (as physically possible) to the measurement plane.
- 6) The DUT's RF emission field was eliminated from T-coil results by using a well RF-shielding of the probe, AM1D, and by using of coaxial cable connection to a Base Station Simulator. One test channel was pre-measurement to avoid this possibility.
- 7) Determined the optimal measurement locations for the DUT by following the three steps, coarse resolution scan, fine resolution scans, and point measurement, as described in C63.19 per 7.4.4.2. At each measurement locations, samples in the measurement window duration were evaluated to get ABM1 and the signal spectrum. The noise measurement was performed after the scan with the signal, the same happened, just with the voice signal switched off. The ABM2 was calculated from this second scan.
- 8) All results resulting from a measurement point in a T-Coil job were calculated from the signal samples during this window interval. ABM values were averaged over the sequence of there samples.
- 9) At an optimal point measurement, the SNR (ABM1/ABM2) was calculated for perpendicular and transverse orientation, and the frequency response was measured for perpendicular.
- 10) Corrected for the frequency response after the DUT measurement since the DASY5 system had known the spectrum of the input signal by using a reference job.
- 11) In SEMCAD postprocessing, the spectral points are in addition scaled with the high-pass (half-band) and the A-weighting, bandwidth compensated factor (BWC) and those results are final as shown in this report.





7 T-Coil PERFORMANCE REQUIREMENTS

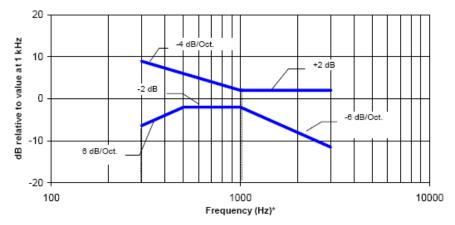
In order to be rated for T-Coil use, a WD shall meet the requirements for signal level and signal quality contained in this part.

7.1 T-Coil coupling field intensity

When measured as specified in ANSI C63.19, the T-Coil signal shall be ≥ -18 dB (A/m) at 1 kHz, ina1/3 octave band filter for all orientations.

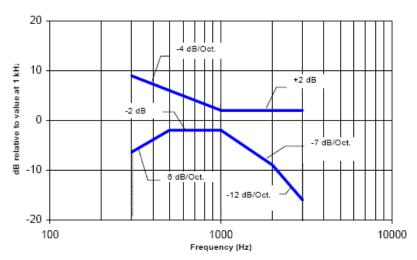
7.2 Frequency response

The frequency response of the axial component of the magnetic field, measured in 1/3 octave bands, shall follow the response curve specified in this sub-clause, over the frequency range 300 Hz to 3000 Hz. Figure 7.1 and Figure 7.2 provide the boundaries for the specified frequency. These response curves are for true field strength measurements of the T-Coil signal. Thus the 6 dB/octave probe response has been corrected from the raw readings.



NOTE-Frequency response is between 300 Hz and 3000 Hz.

Figure 7.1—Magnetic field frequency response for WDs with a field ≤ −15 dB (A/m) at 1 kHz



NOTE-Frequency response is between 300 Hz and 3000 Hz.

Figure 7.2—Magnetic field frequency response for WDs with a fieldthat exceeds -15 dB(A/m) at 1 kHz





7.3 Signal quality

This part provides the signal quality requirement for the intended T-Coil signal from a WD. Only the RF immunity of the hearing aid is measured in T-Coil mode. It is assumed that a hearing aid can have noimmunity to an interference signal in the audio band, which is the intended reception band for this mode. So, the only criteria that can be measured is the RF immunity in T-Coil mode. This is measured using the same procedure as for the audio coupling mode and at the same levels. The worst signal quality of the three T-Coil signal measurements shall be used to determine the T-Coil mode category per Table 1

Table 1:T-Coil signal quality categories

Category	Telephone parameters		
	WD signal quality		
	[(signal + noise) - to - noise ratio in decibels]		
Category T1	0 dB to 10 dB		
Category T2	10 dB to 20 dB		
Category T3	20 dB to 30 dB		
Category T4	> 30 dB		





8 CMRS Voice DUT CONFIGURATION

8.1 GSM Codec Investigation

The middle channel of each frequency band is used for T-coil testing according ANSI C63.19-2011. Choose worst case from radio configuration investigation. After investigation was performed to determine the audio codec configuration to be used for testing, the following tests results which the worst case codec would be remarked to be used for the testing for the DUT. According to C63 and KDB 285076 D02v04, GSM input level is -16dBm0.

Table 8-1 GSM CMRS Codec Investigation

Codec Setting	FR VR	HR V1	EFR	Orientation	Band	Channel
ABM1 (dBA/m)	-6.82	-5.73	-6.25			
Frequency Response	PASS	PASS	PASS	Z(axial)	GSM1900	661
SNR (dB)	36.17	36.83	35.37			

9 HAC T-Coil TEST DATA SUMMARY

9.1 Test Results for 2/3G

Table 13-1 Test results for 2/3G

Probe Position	Band	Ch.	Measurement Position (x mm, y mm)	ABM1 (dB A/m)	SNR (dB)	T category
1 1 1 1 1 1 1 1 1 1	GSM 850	190	-3.7,6.7	-15.96	34.08	T4
transverse	PCS 1900	661	-3.3,5	-17.88	38.26	T4
porpondicular	GSM 850	190	-6.2,0	-6.79	31.59	T4
perpendicular -	PCS 1900	661	-5,0.4	-6.25	35.37	T4

Note:

- 1. Bluetooth and WiFi function is turn off and microphone is muted.
- 2. The volume is adjusted to maximum level during T-Coil testing.

9.2 Total Measurement Conclusion

Probe	Frequency Band(MHz)	ABM1	Frequency Response	T Category
Tronovoro	GSM 850	Pass		T4
Transverse	GSM 1900	Pass	1	T4
Downondioulou	GSM 850	Pass	Pass	T4
Perpendicular	GSM 1900	Pass	Pass	T4





10 MEASUREMENT UNCERTAINTY

No.	Error source	Туре	Uncertainty Value	Prob.	Div.	ABM1	ABM2	Std. Unc.	Std. Unc. ABM2
			a _i (%)	Dist.		ci	ci	(%)	<i>u</i> _i (%)
1	System Repeatability	A	0.016	N	1	1	1	0.016	0.016
Prob	e Sensitivity								
2	Reference Level	В	3.0	R	$\sqrt{3}$	1	1	3.0	3.0
3	AMCC Geometry	В	0.4	R	$\sqrt{3}$	1	1	0.2	0.2
4	AMCC Current	В	0.6	R	$\sqrt{3}$	1	1	0.4	0.4
5	Probe Positioning during Calibration	В	0.1	R	$\sqrt{3}$	1	1	0.1	0.1
6	Noise Contribution	В	0.7	R	$\sqrt{3}$	0. 014 3	1	0.0	0.4
7	Frequency Slope	В	5. 9	R	$\sqrt{3}$	0.1	1	0.3	3.5
Prob	e System			•	•				
8	Repeatability / Drift	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6
9	Linearity / DynamicRange	В	0.6	N	1	1	1	0.4	0.4
10	Acoustic Noise	В	1.0	R	$\sqrt{3}$	0.1	1	0.1	0.6
11	Probe Angle	В	2.3	R	$\sqrt{3}$	1	1	1.4	1.4
12	Spectral Processing	В	0.9	R	$\sqrt{3}$	1	1	0.5	0.5
13	Integration Time	В	0.6	N	1	1	5	0.6	3.0
14	Field Distribution	В	0.2	R	$\sqrt{3}$	1	1	0.1	0.1
Test	Signal								
15	Ref.Signal Spectral Response	В	0.6	R	$\sqrt{3}$	0	1	0.0	0.4
Posit	ioning		_						
16	Probe Positioning	В	1.9	R	$\sqrt{3}$	1	1	1. 1	1. 1
17	Phantom Thickness	В	0.9	R	$\sqrt{3}$	1	1	0.5	0.5





18	DUT Positioning	В	1.9	R	$\sqrt{3}$	1	1	1.1	1.1
Exte	rnal Contributions								
19	RF Interference	В	0.0	R	$\sqrt{3}$	1	0.3	0.0	0.0
20	Test Signal Variation	В	2. 0	R	$\sqrt{3}$	1	1	1.2	1.2
	pined Std. Uncertainty	$u_c^{'} = 0$		$=\sqrt{\sum_{i=1}^{20}}$	$c_i^2 u_i^2$			4. 1	6. 1
Expa	nded Std. Uncertainty	$u_e = 2u_c$		N		<i>k</i> = 2		8. 2	12. 2

11 MAIN TEST INSTRUMENTS

List of Main Instruments

No.	Name	Туре	Serial Number Calibration Date		Valid Period
01	Audio Magnetic 1D Field Probe	AM1DV2	1064	July 19, 2022	One year
02	Audio Magnetic Calibration Coil	AMCC	1064	NCR	NCR
03	Audio Measuring Instrument	АММІ	1044	NCR	NCR
04	HAC Test Arch	N/A	1014	NCR	NCR
05	DAE	SPEAG DAE4	1524	October 17,2022	One year
06	Software	DASY5 V5.0 Build 119.9	N/A	NCR	NCR
07	Software	SEMCAD V13.2 Build 87		NCR	
08	Universal Radio Communication Tester	CMW 500	166370	June28,2022	One year

END OF REPORT BODY





ANNEX A TEST LAYOUT



Picture A1: HAC T-Coil System Layout





ANNEX B TEST PLOTS

T-Coil GSM 850 Transverse

Date: 2023-05-09

Electronics: DAE4 Sn1524

Medium: Air

Medium parameters used: $\sigma = 0$ mho/m, $\varepsilon_r = 1$; $\rho = 1$ kg/m³

Ambient Temperature:22.5°C

Communication System: GSM850; Frequency: 836.6 MHz; Duty Cycle: 1:8.3

Probe: AM1DV2 - 1064;

T-Coil scan (scan for ANSI C63. 19-2007 & 2011 compliance)/General

Scans/y (transversal) 4.2mm 50 x 50/ABM Interpolated Signal(x, y, z)

(121x121x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Signal Type: Audio File (.wav) 48k_voice_1kHz_1s.wav

Output Gain: 37.15

Measure Window Start: 300ms Measure Window Length: 1000ms

BWC applied: 0.16 dB

Device Reference Point: 0, 0, -6.3 mm

Cursor:

ABM1 = -13.86 dBA/mBWC Factor = 0.16 dB

Location: -2.1, -8.3, 3.7 mm

T-Coil scan (scan for ANSI C63.19-2007 & 2011 compliance)/General

Scans/y (transversal) 4.2mm 50 x 50/ABM Interpolated SNR(x, y, z)

(121x121x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Signal Type: Audio File (.wav) 48k_voice_1kHz_1s.wav

Output Gain: 37.15

Measure Window Start: 300ms Measure Window Length: 1000ms

BWC applied: 0.16 dB

Device Reference Point: 0, 0, -6.3 mm





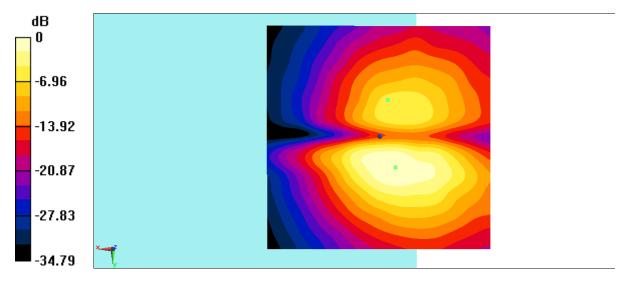
Cursor:

ABM1/ABM2 = 34.08 dB

ABM1 comp = -15.96 dBA/m

BWC Factor = 0.16 dB

Location: -3.7, 6.7, 3.7 mm



0 dB = 0.2028 A/m = -13.86 dBA/m

Fig B.1 T-Coil GSM 850





T-Coil GSM 850 Perpendicular

Date: 2023-05-09

Electronics: DAE4 Sn1524

Medium: Air

Medium parameters used: $\sigma = 0$ mho/m, $\varepsilon_r = 1$; $\rho = 1$ kg/m³

Ambient Temperature:22.5°C

Communication System: GSM850; Frequency: 836.6 MHz; Duty Cycle: 1:8.3

Probe: AM1DV2 - 1064;

T-Coil scan (scan for ANSI C63. 19-2007 & 2011 compliance)/General

Scans/z (axial) 4.2mm 50 x 50/ABM Interpolated Signal(x, y, z)

(121x121x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Signal Type: Audio File (.wav) 48k_voice_1kHz_1s.wav

Output Gain: 37.15

Measure Window Start: 300ms Measure Window Length: 1000ms

BWC applied: 0.16 dB

Device Reference Point: 0, 0, -6.3 mm

Cursor:

ABM1 = -5.76 dBA/mBWC Factor = 0.16 dB

Location: -2.5, 0.4, 3.7 mm

T-Coil scan (scan for ANSI C63.19-2007 & 2011 compliance)/General

Scans/z (axial) 4.2mm 50 x 50/ABM Interpolated SNR(x, y, z)

(121x121x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Signal Type: Audio File (.wav) 48k_voice_1kHz_1s.wav

Output Gain: 37.15

Measure Window Start: 300ms Measure Window Length: 1000ms

BWC applied: 0.16 dB

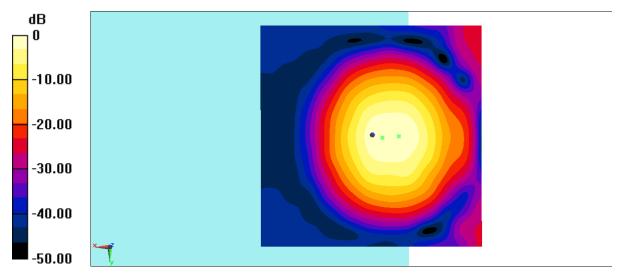
Device Reference Point: 0, 0, -6.3 mm





Cursor:

ABM1/ABM2 = 31.59 dB ABM1 comp = -6.79 dBA/m BWC Factor = 0.16 dB Location: -6.2, 0, 3.7 mm



0 dB = 0.5155 A/m = -5.76 dBA/m

Fig B.2 T-Coil GSM 850





ANNEX C FREQUENCY REPONSE CURVES

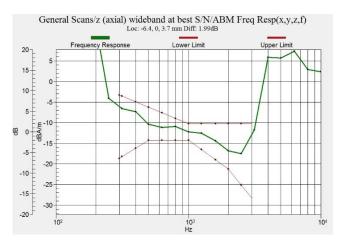


Figure C.1 Frequency Response of GSM 850





ANNEX D PROBE CALIBRATIONCERTIFICATE

Calibration Laboratory of Schmid & Partner **Engineering AG** Zeughausstrasse 43, 8004 Zurich, Switzerland





Schweizerischer Kalibrierdienst S Service suisse d'étalonnage C Servizio svizzero di taratura S Swiss Calibration Service

Accreditation No.: SCS 0108

Accredited by the Swiss Accreditation Service (SAS) The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Certificate No: AM1DV2-1064_Jul22 CTTL (Auden) **CALIBRATION CERTIFICATE** AM1DV2 - SN: 1064 Object QA CAL-24.v4 Calibration procedure(s) Calibration procedure for AM1D magnetic field probes and TMFS in the audio range July 19, 2022 Calibration date: This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate. All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%. Calibration Equipment used (M&TE critical for calibration) Cal Date (Certificate No.) Scheduled Calibration Primary Standards 31-Aug-21 (No. 31368) SN: 0810278 Aug-22 Keithley Multimeter Type 2001 28-Dec-21 (No. AM1DV2-1008_Dec21) Dec-22 SN: 1008 Reference Probe AM1DV2 22-Dec-21 (No. DAE4-781_Dec21) Dec-22 DAE4 SN: 781 Scheduled Check ID# Check Date (in house) Secondary Standards SN: 1050 01-Oct-13 (in house check Oct-20) Oct-23 AMCC Oct-23 26-Sep-12 (in house check Oct-20) AMMI Audio Measuring Instrument | SN: 1062 Function Name Laboratory Technician Calibrated by: Leif Klysner Quality Manager Niels Kuster Approved by: Issued: July 20, 2022 This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: AM1DV2-1064 Jul22

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References

- [1] ANSI-C63.19-2007
 - American National Standard for Methods of Measurement of Compatibility between Wireless Communications Devices and Hearing Aids.
- [2] ANSI-C63.19-2019 (ANSI-C63.19-2011)
 American National Standard, Methods of Measurement of Compatibility between Wireless
 Communications Devices and Hearing Aids.
- [3] DASY System Handbook

Description of the AM1D probe

The AM1D Audio Magnetic Field Probe is a fully shielded magnetic field probe for the frequency range from 100 Hz to 20 kHz. The pickup coil is compliant with the dimensional requirements of [1+2]. The probe includes a symmetric low noise amplifier for the signal available at the shielded 3 pin connector at the side. Power is supplied via the same connector (phantom power supply) and monitored via the LED near the connector. The 7 pin connector at the end of the probe does not carry any signals, but determines the angle of the sensor when mounted on the DAE. The probe supports mechanical detection of the surface.

The single sensor in the probe is arranged in a tilt angle allowing measurement of 3 orthogonal field components when rotating the probe by 120° around its axis. It is aligned with the perpendicular component of the field, if the probe axis is tilted nominally 35.3° above the measurement plane, using the connector rotation and sensor angle stated below. The probe is fully RF shielded when operated with the matching signal cable (shielded) and allows measurement of audio magnetic fields in the close vicinity of RF emitting wireless devices according to [1+2] without additional shielding.

Handling of the item

The probe is manufactured from stainless steel. In order to maintain the performance and calibration of the probe, it must not be opened. The probe is designed for operation in air and shall not be exposed to humidity or liquids. For proper operation of the surface detection and emergency stop functions in a DASY system, the probe must be operated with the special probe cup provided (larger diameter).

Methods Applied and Interpretation of Parameters

- Coordinate System: The AM1D probe is mounted in the DASY system for operation with a HAC Test Arch phantom with AMCC Helmholtz calibration coil according to [3], with the tip pointing to "southwest" orientation.
- Functional Test: The functional test preceding calibration includes test of Noise level RF immunity (1kHz AM modulated signal). The shield of the probe cable must be well connected. Frequency response verification from 100 Hz to 10 kHz.
- Connector Rotation: The connector at the end of the probe does not carry any signals and is used for fixation to the DAE only. The probe is operated in the center of the AMCC Helmholtz coil using a 1 kHz magnetic field signal. Its angle is determined from the two minima at nominally +120° and 120° rotation, so the sensor in the tip of the probe is aligned to the vertical plane in z-direction, corresponding to the field maximum in the AMCC Helmholtz calibration coil.
- Sensor Angle: The sensor tilting in the vertical plane from the ideal vertical direction is determined from the two minima at nominally +120° and −120°. DASY system uses this angle to align the sensor for radial measurements to the x and y axis in the horizontal plane.
- Sensitivity: With the probe sensor aligned to the z-field in the AMCC, the output of the probe is
 compared to the magnetic field in the AMCC at 1 kHz. The field in the AMCC Helmholtz coil is
 given by the geometry and the current through the coil, which is monitored on the precision shunt
 resistor of the coil.

Certificate No: AM1DV2-1064_Jul21 Page 2 of 3





AM1D probe identification and configuration data

Item	AM1DV2 Audio Magnetic 1D Field Probe
Type No	SP AM1 001 AF
Serial No	1064

Overall length	296 mm
Tip diameter	6.0 mm (at the tip)
Sensor offset	3.0 mm (centre of sensor from tip)
Internal Amplifier	40 dB

Manufacturer / Origin	Schmid & Partner Engineering AG, Zurich,	Switzerland
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Calibration data

Connector rotation angle	(in DASY system)	100.6°	+/- 3.6 ° (k=2)
Sensor angle	(in DASY system)	0.36 °	+/- 0.5 ° (k=2)
Sensitivity at 1 kHz	(in DASY system)	0.0658 V/(A/m)	+/- 2.2 % (k=2)

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

Certificate No: AM1DV2-1064_Jul21

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ANNEX E DAE CALIBRATION CERTIFICATE



Add: No.52 HuaYuanBei Road, Haidian District, Beijing, 100191, China Tel: +86-10-62304633-2117

E-mail: emf@caict.ac.cn Client :

http://www.caict.ac.cn

Certificate No: Z22-60463



CALIBRATION CERTIFICATE

Object DAE4 - SN: 1524

Calibration Procedure(s) FF-Z11-002-01

Calibration Procedure for the Data Acquisition Electronics

(DAEx)

Calibration date: October 17, 2022

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)°C and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Scheduled Calibration Primary Standards ID# Cal Date(Calibrated by, Certificate No.) 14-Jun-22 (CTTL, No.J22X04180) Jun-23 Process Calibrator 753 1971018

SAR Test Engineer

SAR Test Engineer

Function Name Calibrated by:

Yu Zongying Reviewed by:

Lin Hao

Approved by: Qi Dianyuan SAR Project Leader

Issued: October 19, 2022

Signature

This calibration certificate shall not be reproduced except in full without written approval of the laboratory

Certificate No: Z22-60463

Page 1 of 3









Add: No.52 HuaYuanBei Road, Haidian District, Beijing, 100191, China Tel: +86-10-62304633-2117

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Glossary:

DAE data acquisition electronics

Connector angle information used in DASY system to align probe sensor X

to the robot coordinate system.

Methods Applied and Interpretation of Parameters:

- DC Voltage Measurement: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- Connector angle: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The report provide only calibration results for DAE, it does not contain other performance test results.

Certificate No: Z22-60463 Page 2 of 3









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DC Voltage Measurement

A/D - Converter Resolution nominal

6.1μV, 61nV, High Range: 1LSB = full range = -100...+300 mV Low Range: 1LSB = 61nV, full range = -1......+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	х	Y	Z
High Range	406.127 ± 0.15% (k=2)	405.356 ± 0.15% (k=2)	405.663 ± 0.15% (k=2)
Low Range	3.99143 ± 0.7% (k=2)	4.01873 ± 0.7% (k=2)	3.99477 ± 0.7% (k=2)

Connector Angle

Connector Angle to be used in DASY system	83° ± 1 °
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The photos of HAC test are presented in the additional document:

Appendix to test report No.I23Z60867-SEM02/03

The photos of HAC test