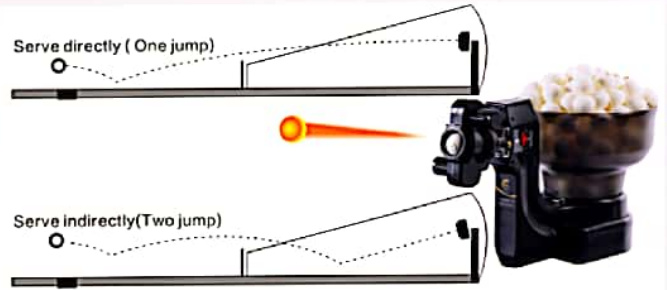


## Function Introduction

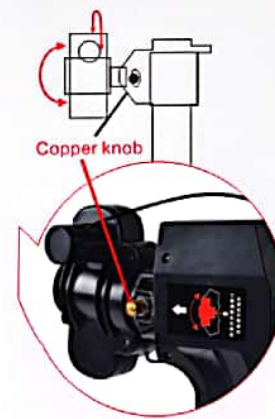


Serve Type Diagram

Serve type: Serve directly and Serve indirectly

Indirectly type : With a proper speed and spin ,it is much more suitable for beginners to practice different skills of serving and receiving balls.

Directly type : Compare with indirectly type ,it is stronger on its radian and spin. You have to loosen the copper button when you adjust the height of the robot head. You can get different radian balls. When the robot head is swinging ,don't adjust it by hand.

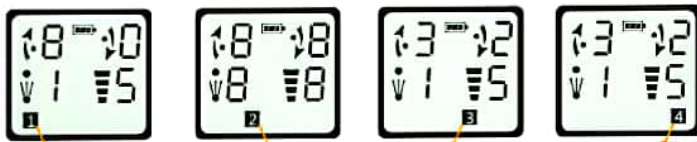


Must loosen the copper knob when you adjust the elevation of robot head.  
No adjustment when it is working .



Adjusting the speed of top-wheels & bottom-wheels and the direction of the robot heads can rotate the robot. Robot can serve 9 spin balls and 1 non-spin. The head can oscillate between 180 angles(horizontal line).

1 Position: The rotation of top-wheel is top spin, of the bottom-wheel is the under spin. With the same position is non-spin.  
2. Position: The rotation of top-wheel is left spin, of the bottom-wheel is the right spin. With the same position is non-spin.  
3. Position: The rotation of top-wheel is right spin, of the bottom-wheel is the left spin. With the same position is non-spin.  
Adjust two wheels and speed between 1 to 2 or between 1 to 3 ,can combine different kinds of spins.



One button topspin

One button underspin

direct service (non-spin)

irregular service

## Fault Handling

Fault phenomenon	Failure cause	Treating method
Power with no reation	Power failure	Replace power supply
	Connection is not good	Replug power cord
Balls are not out	Ball groove is dirty	Take down the robot head ,then clean the ball groove and balls
	Balls are broken,dirty or not standard	Change to standard 40mm new balls
	Motor is broken	Replace
	Speed changing box is broken	Replace
Serve ball weakly	Motor for serving ball is broken	Replace
	Connection of power socket is not good	Replug
	Line of the motor is disconnected	Replug
No oscillation	Motor of oscillation is broken	Replace
	Speed changing box is broken	Replace
	Connection of power socket is not good	Replug
	Line of the motor is disconnected	Replug
Oscillation range is small	Adjusting rod is error	Reset
Start button with no reation/Speed button with no reation	Control box is broken	Replace



## Notes

- Children must use the robot correctly by the guide of adults or parents.
- Please use the standard 40 mm balls. You can choose Suzhi training balls or other more than one star balls. Please don't use the balls that are too soft or irregular to avoid clamping balls.
- Please clean the new balls with clear water or cleaning agent and dry them before you use them. And clean the balls and the ball groove termly to keep the machine clean and reduce the failure.
- Please add the balls to the storage tube when the machine is off to avoid clamping balls.
- If you don't use the robot in a long time ,please clean it up and with good storage bags.
- If you have any problems ,please contact our after-sale service.



扫描全能王 创建



# SUZ S102 USER MANUAL

## Technical Parameters

G.W :4.5KG  
 N.W: 3.3KG  
 Packing Dimensions : L40\*W 38\*H37  
 Rated Voltage :100-240V  
 Rated Power :36W  
 Spin: Topspin , underspin , non-spin , left and right sidespin  
 Serving Frequency :40-70/Min  
 Serving Speed 4-35m/s  
 The most balls : 120 balls  
 The fewest balls : 10 balls  
 Point of fall : Random  
 Colors : Black

Can serve 9 spin balls and 1 non-spin ball  
 Can be up and down to adjust the angle of serving ball  
 Can be left and right to adjust the angle of serving ball

## Standard Accessories



- A · Main engine
- B · Robot head
- C · Ball storage tube
- D · Power
- E · Fixed frame
- F · Telecontroller
- G · User manual

## Installation



Step 1. Unpack and check the accessories



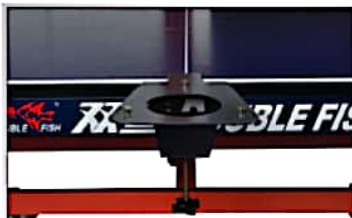
Step 2. Connect the robot head to the main engine ,then fix it with the fixed cover and screw it.



Step 3. Connect the USB line to the port of the main engine.



Step 4. Fix the ball storage tube to the main engine and rotate to fix it.



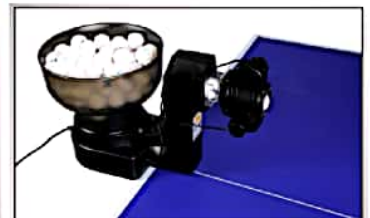
Step 5. Take out the fixed frame and install to the standard table.



Step 6. Fix the robot to the fixed frame



Step 7. Link the power line .



Step 8 . Finish line .

## SUZ Sporting Goods Co.,Ltd

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 Web: www.huipang.net



扫描全能王 创建

## FCC STATEMENT :

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

This device may not cause harmful interference, and

This device must accept any interference received, including interference that may cause undesired operation.

Warning: Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

Reorient or relocate the receiving antenna.

Increase the separation between the equipment and receiver.

Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.

Consult the dealer or an experienced radio/TV technician for help.

## RF warning statement:

The device has been evaluated to meet general RF exposure requirement. The device can be used in portable exposure condition without restriction.

