



Space Dynamics
LABORATORY
Utah State University Research Foundation

FCC FORM 442: Exhibit A

FlexSAR-X Experimentation Description

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1. INTRODUCTION

The Space Dynamics Laboratory (SDL) submits this document as Exhibit A of FCC Form 442 and in accordance with Section 5.3(b), (d) and (h) of CFR Title 47 for the purpose of testing and further developing its Flexible Synthetic Aperture Radar (FlexSAR-X), which operates between 9.5 and 10 GHz . SDL respectfully requests a 2-year license beginning June 1, 2013. This document provides supporting information and justification for the license application.

2. PROGRAM OF RESEARCH DESCRIPTION

The FlexSAR-X program is a development effort funded internally at SDL. The objective is to build and test a SAR system that is capable of working in X-band as a research tool for airborne SAR applications.

2.1 EQUIPMENT DESCRIPTION

The FlexSAR-X system consists of a Versa Module Eurocard (VME) chassis, solid state power amplifiers (SSPA) and an antenna. The VME chassis is 19"W x 15.75"H x 19.5"D, weighs 40 lbs and contains cards that provide a stable local oscillator, frequency conversion, pulse generation, analog to digital conversion, signal processing, and command and control. A chirp pulse is generated by direct digital synthesis (DDS) as it sweeps from low to high frequency, then up-converted to L-band and finally up-converted to X-band. The receiver reverses the process by down-converting from X-band to L-band and then from L-band to baseband. Bandpass and lowpass filters are incorporated on each stage of the transmitter and receiver to suppress unwanted out-of-band frequencies. The SSPA is only enabled during transmission of a pulse.

Each antenna polarization, horizontal and vertical (H and V), has a dedicated channel. The transmitter and receiver share the same antenna polarizations and are isolated from each other by a circulator. Each channel is connected to an SSPA before being connected to the antenna through the circulator. The FRF-138, an X-band antenna built by First RF Corp, is used for transmit and receive.



Figure 1. The FlexSAR-X VME chassis.

The FlexSAR-X system specifications are detailed in Table 1.

Table 1. FlexSAR-X Specifications

RF Hardware	Space Dynamics Laboratory
Frequency	9500 to 10,000 MHz
Waveform Modulation	Pulse
Peak Transmitter Power	25 W (44 dBm)
Avg Transmitter Power	2.4 W (3.8 dBm) (typ)
Pulse Repetition	16,000 pps (typ), 20,000 pps (max)
Transmitter Type	Linear Frequency Modulated Pulse
Transmitter Tuning	Direct Digital Synthesizer
Transmitter Frequency	0.0000001 ppm
Transmitter Power Amp	
Manufacture	Aethercomm
Model Number	SSPA 9.5-10.5-25
Transmitter Harmonic	
2 nd (dBc)	-60.4
Maximum Spurious	-70.0
Fundamental Curve	
-3.0 dBc	9560.10, 10085.00 MHz
-20 dBc	9543.00, 10130.68 MHz
-40 dBc	9513.00, 10155.80 MHz
-60 dBc	9459.00, 10185.95 MHz
Transmitter Filter	Bandpass, pre-power amplifier
Antenna Manufacture	First RF Corp
Antenna Model Number	FRF-138
Antenna Gain	18.0 dBi
Antenna Beamwidth	
Horizontal	40 degrees
Vertical	10 degrees
Antenna Mounting	Antennas are aircraft-mounted, under aircraft

2.2 THEORY OF OPERATION

The FlexSAR-X system collects data from an airborne platform while being controlled by an onboard operator. The RF card chassis is mounted inside the aircraft, and the antenna is mounted on the left side of the fuselage with a pointing vector perpendicular to the flight

direction and slanted downward 45 to 60 degrees, as shown in **Error! Reference source not found.** During the pre-flight planning process, areas of interest are identified that present scenes and objects to test the imaging fidelity of the SAR system.

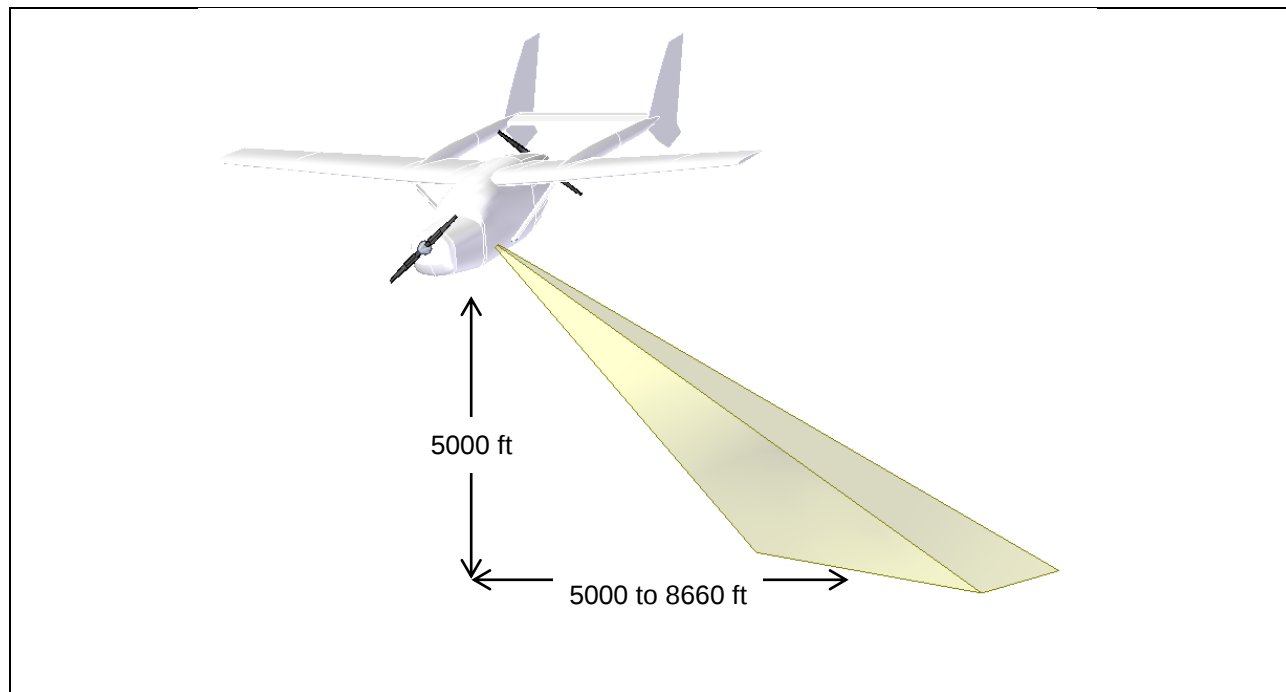


Figure 2. The antenna is mounted such that energy is directed to the left and angled downward towards the ground.

FlexSAR-X can operate in one of four modes:

1. Transmit on H polarization and receive on H polarization (HH)
2. Transmit on V polarization and receive on V polarization (VV)
3. Alternate between modes 1 and 2 above for every other pulse, which is called interleaved mode (HH/VV)
4. Alternate transmitting on H and V polarizations every other pulse but receive on both H and V polarization channels. This is called quadrature mode (HH HV/VH VV)

The aircraft typically flies a race-track pattern around the area of interest, with FlexSAR-X actively transmitting and receiving energy during the straight portion of the track, as shown in Figure 3. Top-down view of a typical flight path used to collect data of an area of interest. The race-track pattern is pre-planned to present the scene at a nominal altitude and slant range. Typical operating altitude is 5000 ft AGL with slant ranges of 5000 to 8660 ft. The onboard operator monitors the aircraft position and heading to determine when the areas of interest enter the beam of the antenna. The operator turns on and off the transmitter when the area of interest enters and leaves the beam, respectively. The system operation modes and transmit on/off are controlled by the operator from a software application developed by SDL, but there are also panel switches that can disable the transmitter in the event the software is not functioning. The operator is an experienced member of SDL staff.

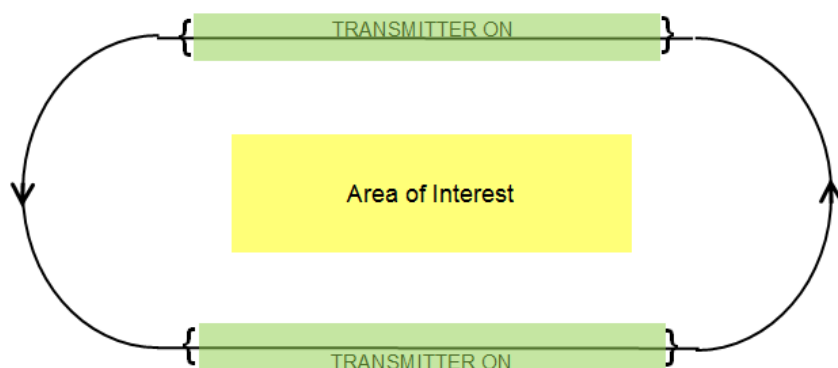


Figure 3. Top-down view of a typical flight path used to collect data of an area of interest.

3. DESCRIPTION OF EXPERIMENT

3.1 EXPERIMENT OBJECTIVES

The primary purpose for flight testing the FlexSAR-X system is to observe system performance in a real-world environment. This includes the characterization of key metrics, such as signal-to-noise ratio, and provides feedback for engineering further improvements. Also, it is desired to obtain a better understanding of how system parameters affect the sensor's ability to resolve certain objects of interest in different clutter backgrounds.

3.2 PROPOSED LOCATIONS

SDL seeks authority to carry out its test flights in two locations as specified in the table and shown on the map in Figure 4. The areas were chosen due to the variety of natural and man-made scenes that will exercise the FlexSAR-X system's capability. The areas are defined by a center coordinate and radius as follows:

Table 2. Location Specifications

	Center Latitude	Center Longitude	Radius (km)	Altitude (ft)
Logan	41°46'42"	111°51'12"	40	<8200 AGL
Great Salt Lake	40°59'45"	112°52'51"	60	<8200 AGL

A map of the proposed location and the surrounding area is shown in Figure 4. A license was recently granted for a similar location and frequency band (File #: 0647-EX-PL-2012).

5. CONTACT INFORMATION

Questions regarding this application should be referred to the following individuals.

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