

File # 0202-EX-CN-2021 Response to FCC RFI (Received on April 2, 2021)



Project Summary

- Implement and evaluate experimental wireless networks, for voice, video & data comms., between UEs (e.g. cell phones) within a defined coverage area, through a node on a UAV.
 - The UAV will fly in a loiter path over an area of approximately 1km diameter, or less, at altitudes of 500m, or less, centered on the test site ground location.
 - Multiple UEs will be deployed within a 1km radius area at the location.
 - Manual and auto-flight operations will be conducted in accordance with FAA guidelines and FAA authorization.
 - Target applications include Private, IoT and Emergency Networks.
- Two network configurations will be evaluated;
 - Configuration 1: A single band transceiver, with e-node B functionality, will be carried in a UAV. 2x2 MIMO directional antennae (6-9 dBi gain) will be fixed to the underside of the UAV in a downward orientation.
 - Configuration 2: A dual band transceiver, for both uplink and downlink communications will be carried in a UAV. e-node B functionality will be located in a ground station. 2x2 MIMO antenna, similar to Configuration 1, will be mounted on the UAV. The ground station antenna will be an upward-pointing MMIMO array, which can track the UAV.
- Network equipment will consist of COTS and vendor-supplied prototypes.
 - Equipment and configurations will be pre-tested in the lab prior to UAV deployment

Project Summary (cont.)

- Prior to flight testing, we will seek permission from licensed users in the area.
- Testing will be done in two remote areas to minimize the potential for user conflicts.
- Both test sites have dedicated runways, launch, landing and operation facilities.
- The maximum duration of each test is expected to be no more than a few hours.
- Potential interference will also be reduced by restricting the coverage area by,
 - Implementing tight loiter flight plans
 - Setting the directionality of the UAV and ground station antennae.
- We will also deploy a base station analyzer at the test site, to monitor any activity in the operating frequency range prior to, and during, testing.
 - If activity is detected prior to flight, we will either migrate our transmission to an unused part of the approved band, or void the experiment.
 - If activity is detected during flight, the transmission will be terminated, by remotely interrupting the electrical power to the transmitter on the UAV.

Network Configuration 1



Proprietary

Network Configuration 2



Proprietary

Network Equipment Examples

- Transcievers
 - Deltenna: BlackWolf R2 (UAV)
 - Prototype Small Cell (UAV)
 - Prototype (MMIMO Ground Station)
- Antenna
 - Cell-Fi: MIMO panel antenna #A52-X12-100
 - L-Com: MIMO panel antenna # HG72708XWPP-NF
 - Prototype MIMO (UAV) & MMIMO (ground station)

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Please provide additional detailed information regarding the following:

- 1. The purpose and detailed prescriptions of the proposed operation.
- 2. Explanation of how it would coordinate any usage with the AWS, EBS and BRS licensees for the proposed operations.
- 3. An engineering analysis and explanation of how it would specifically avoid causing harmful interference to incumbent AWS, EBS and BRS operations.
- 4. Stop buzzer information just in case interference occurs.



- 1. The purpose and detailed prescriptions of the proposed operation
 - See preceding slides



- 2. Explanation of how it would coordinate any usage with the AWS, EBS and BRS licensees for the proposed operations.
 - We will request permission in advance from licensees



- 3. An engineering analysis and explanation of how it would specifically avoid causing harmful interference to incumbent AWS, EBS and BRS operations.
 - Network performance will be modelled to assess the potential for interference.
 - Testing will be conducted in remote locations with restricted coverage.
 - Testing will be of short duration, and may be scheduled for low traffic periods
 - We will employ a JDSU Base Station Analyser, to monitor any activity in the frequency range before, and during, testing. If a conflict is detected, we will migrate to a non-conflicting frequency or terminate the test.





4. Stop buzzer information just in case interference occurs.

- The avionics on the UAV automatically power down the payloads, if the telemetry and navigation is compromised. The UAV can be preprogrammed to "return to base" if an issue persists.
- A power down signal can also be sent from the on-ground flight control station, for any reason, including potential conflicts with other users, detected on the Base Station Analyzer.

